

# **Evaluation of Advance Warning Signal Installation Phase I Summary Presentation**

**PREPARE  
TO STOP**

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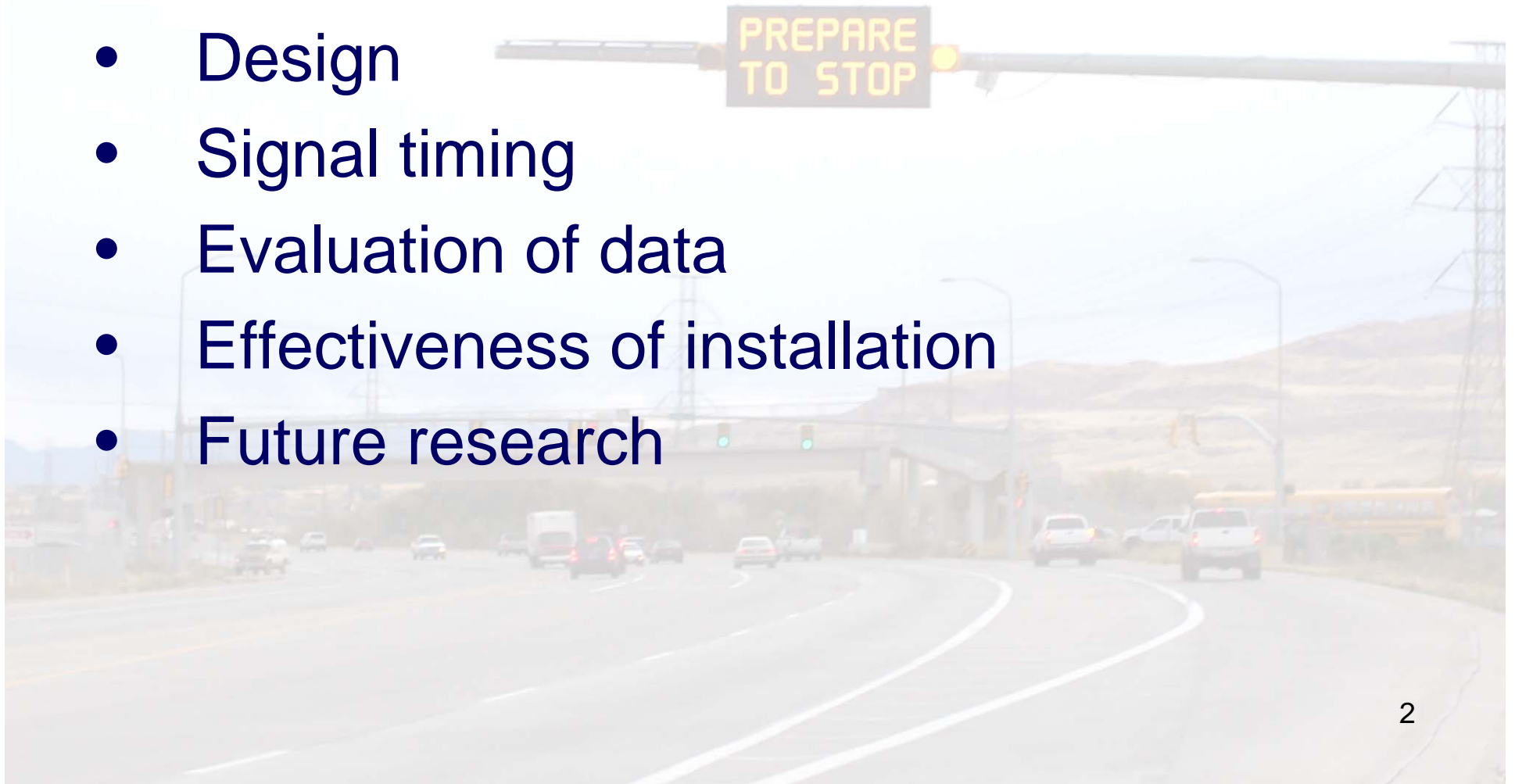


June 2006



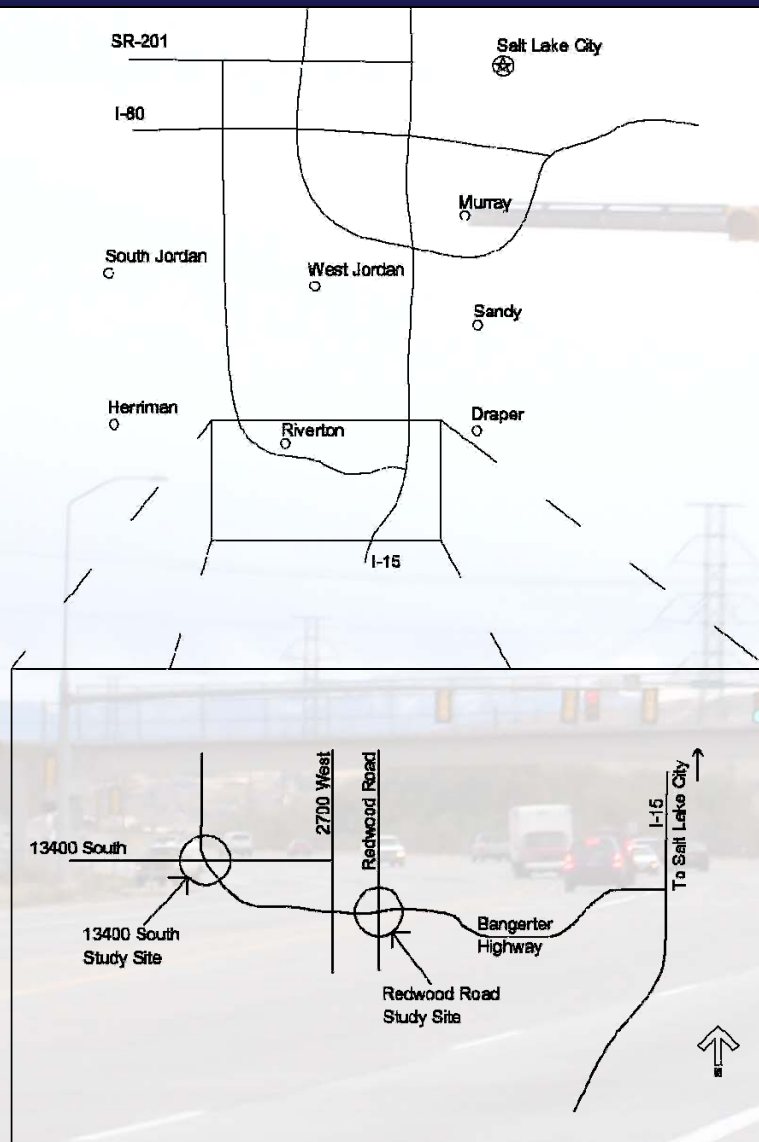
# OVERVIEW

- Background
- Design
- Signal timing
- Evaluation of data
- Effectiveness of installation
- Future research



# BACKGROUND

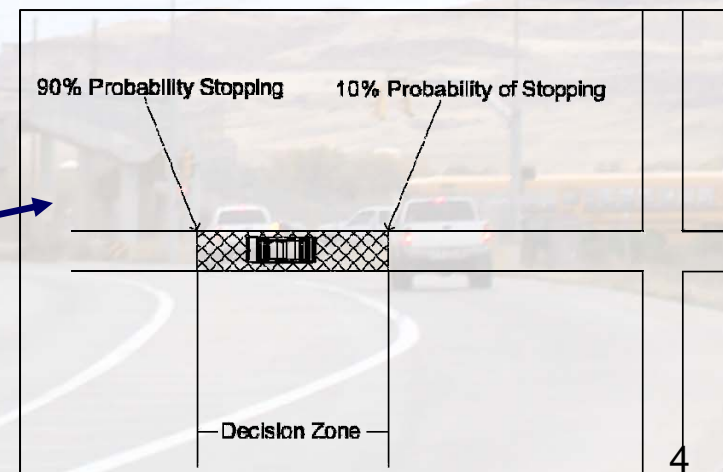
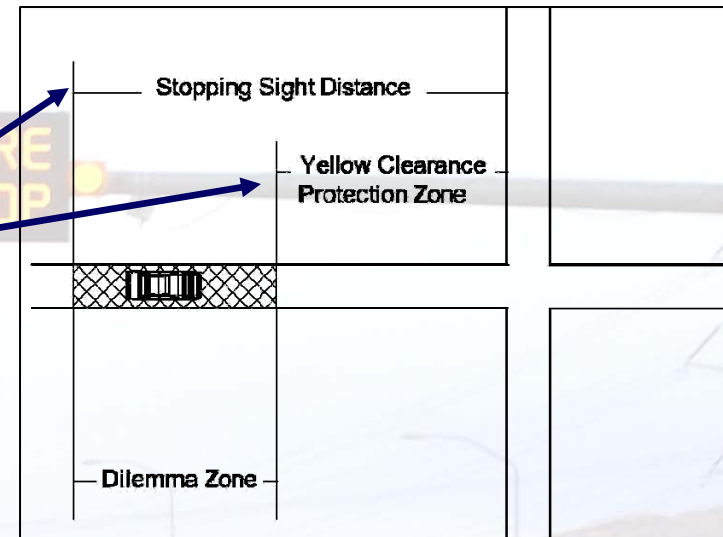
## Site Location



# BACKGROUND

## *Safety Concerns at Signalized Intersections*

- Dilemma zone (DMZ):
  - Not enough distance to stop
  - Not enough time to proceed
  - Improper signal timing
- Decision zone (DCZ):
  - Variation in driver behavior
  - Design assumptions not met
  - Motorists caught unaware
  - 90% - 10% probability stopping distances





# BACKGROUND

## *Mitigation Techniques*

- Advanced detection:
  - Reduce the number of vehicles caught in the DMZ at the onset of yellow
- Advance warning signals:
  - Warn motorists of impending signal changes in an effort to reduce the variation in motorist behavior



# DESIGN

- Design of the project was completed by Project Engineering Consultants, Ltd.



- Three locations on Bangerter Highway:
  - Redwood Road
  - 2700 West
  - **13400 South**
- One location on SR-201
- All intersections have posted speeds of 60 mph
- 85<sup>th</sup> percentile speeds were 63-64 mph

# DESIGN

*Study Location*



**Bangerter Highway and 13400 South**



# DESIGN

## *The Signs*

- “Blank-Out” LED with side-mounted flashers
- Two rows of 14” letters
- 48” x 96” x 12”  
300 lbs
- State-Furnished Item





# DESIGN

## *The Installation*

- Standard 75' mast arm and signal pole with mast arm cut to 55' length
- Horizontal damping “wing” at end of arm (2' x 8' panel)
- 65 mph design speed
- AWS placed 445' from stop bar; luminaire and video camera at 705'; detection zone at 755':
  - Based on a 2002 Nebraska Department of Roads study



# DESIGN

## Typical AWS Layout



# SIGNAL TIMING

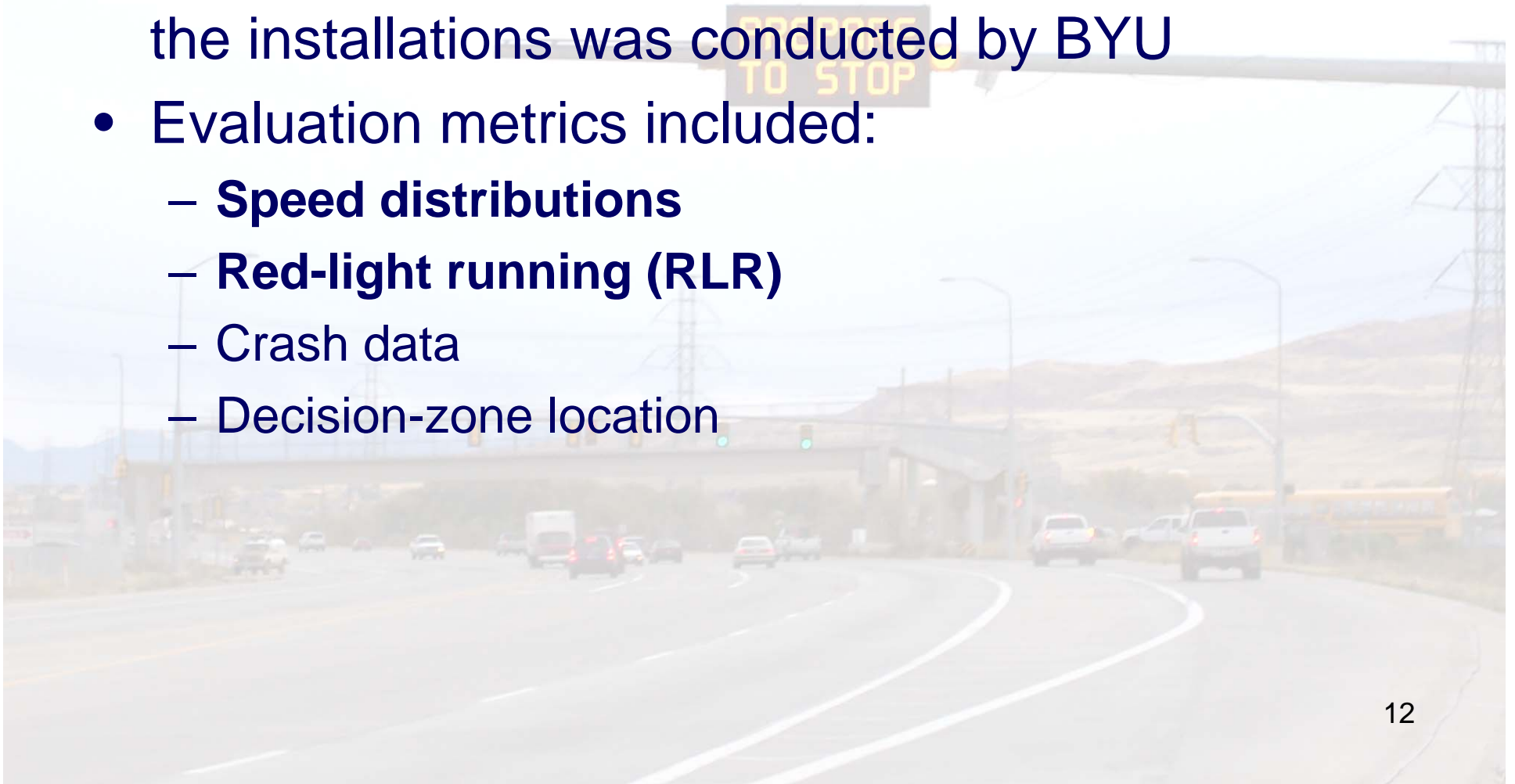
- AWS comes on 6 seconds before end of green (lead-flash time)
- AWS remains on during the red
- AWS turns off once arterial turns green





# EVALUATION

- Evaluation of the data and the effectiveness of the installations was conducted by BYU
- Evaluation metrics included:
  - **Speed distributions**
  - **Red-light running (RLR)**
  - Crash data
  - Decision-zone location

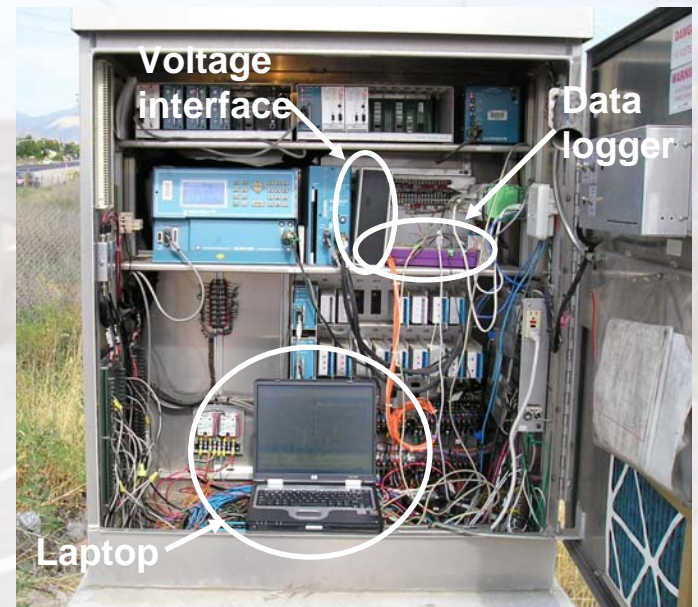
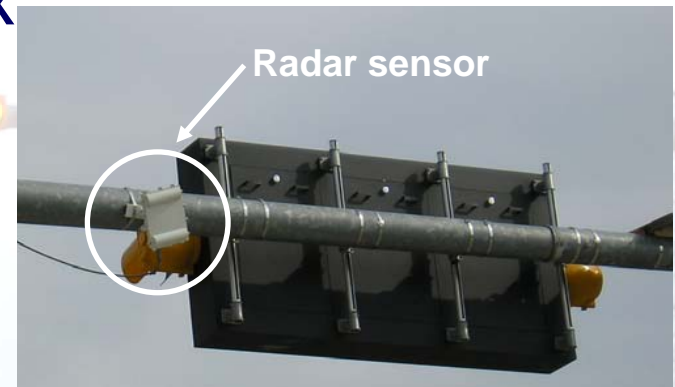




# EVALUATION

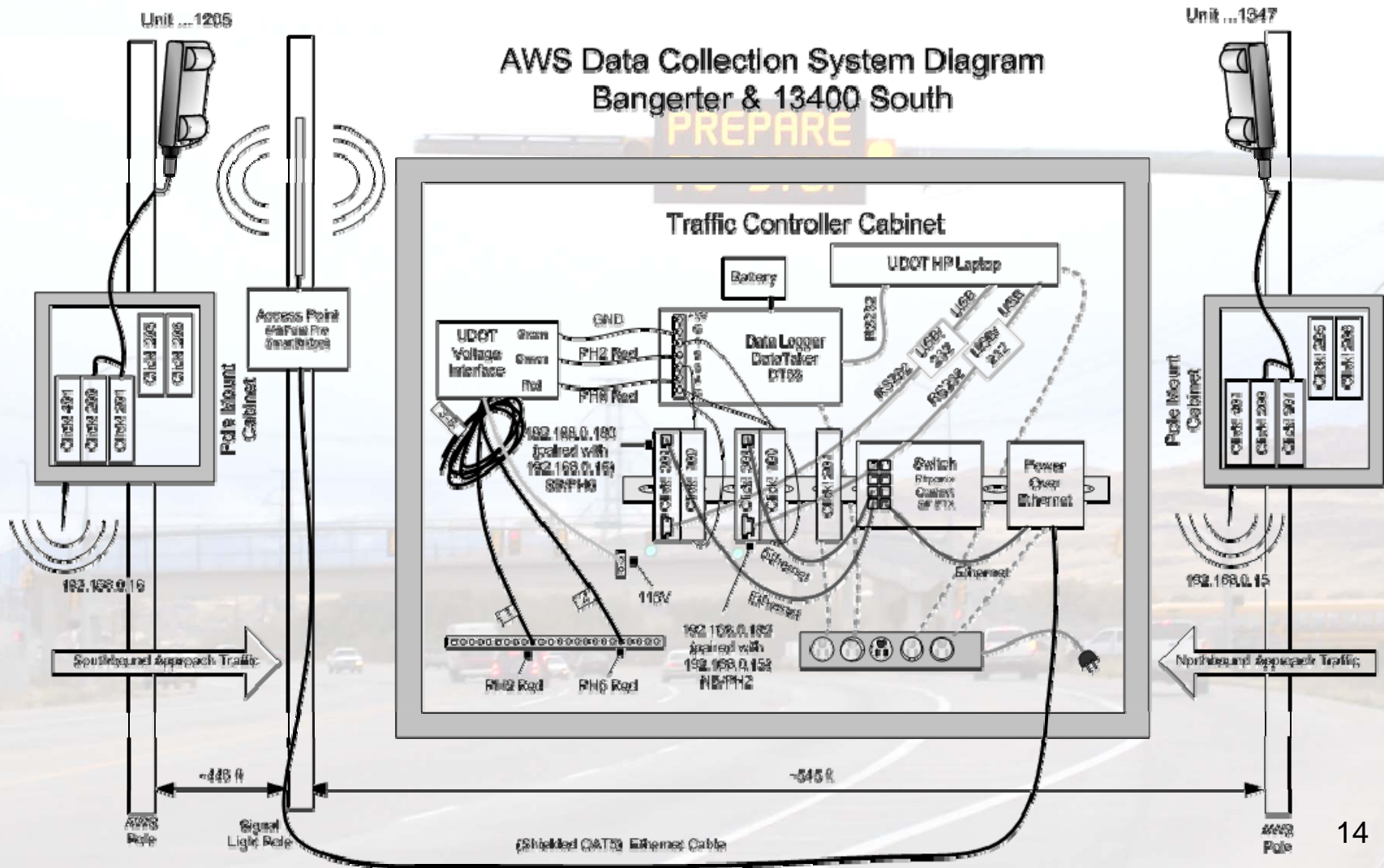
## *Data Collection Equipment – 13400 South*

- BYU partnered with Wavetronix LLC to collect data using:
  - SmartSensor Advance™ digital wave radar
  - Wireless communication devices
  - Contact closure devices
- In addition, UDOT provided the following equipment:
  - Voltage interface
  - Data logger
  - Laptop computer



# EVALUATION

## Data Collection Equipment – 13400 South



# EVALUATION

*Data Collection Equipment – 13400 South*

- Speeds are recorded for each vehicle in 8 zones
- Red signal phases are time stamped
- Signal data is logged in the datalogger
- Speed data is logged on the laptop computer
- Post processing of the signal data and speed data allows red-light runners to be identified



# EVALUATION

## *Data Collection*

- Data was collected for several months prior to activation of the system
- System activation occurred in June 2005 with data collected continuously since activation
- Data analysis included:
  - Before activation
  - Immediately after activation
  - 8 months after activation

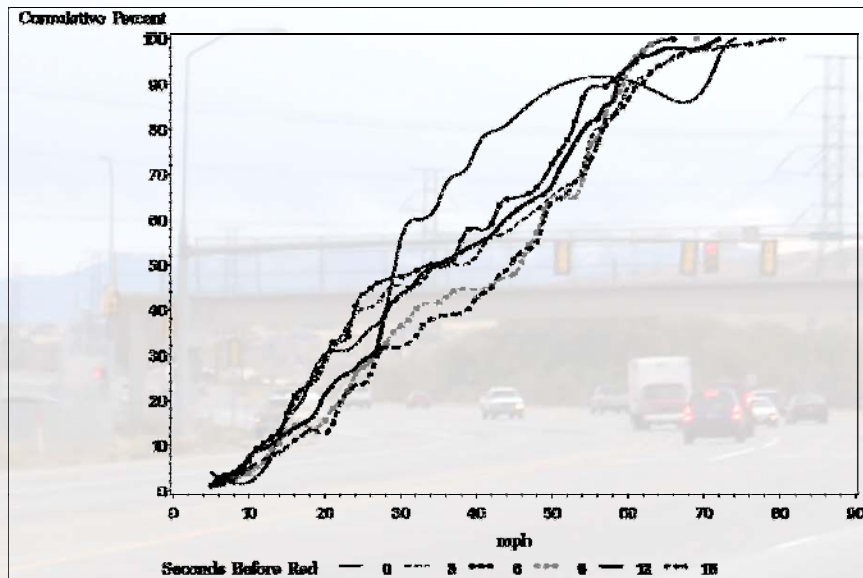


# EFFECTIVENESS

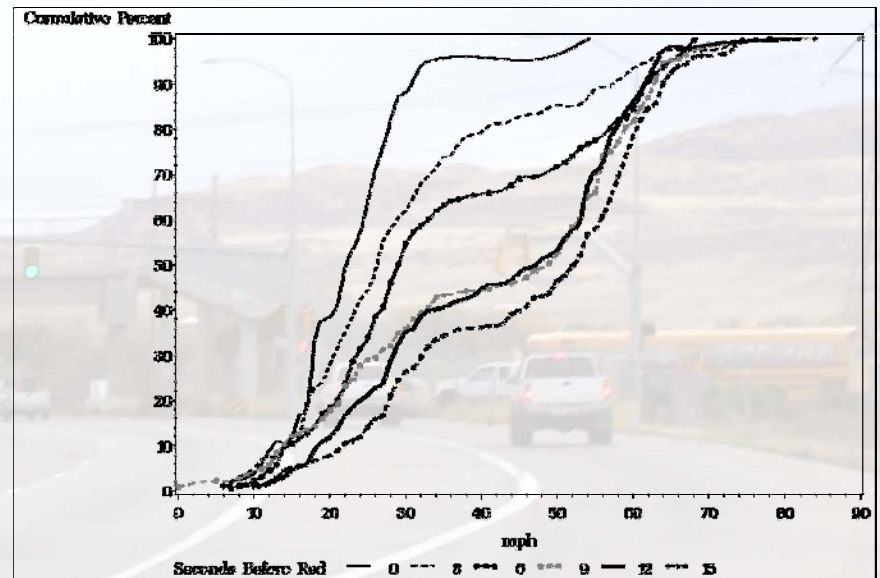
*Preliminary Results at 13400 South*

- Speed data cumulative distributions:
  - Organized by time of day, approach, sensor zone, and number of seconds before red

**Before, Northbound, 100 ft**



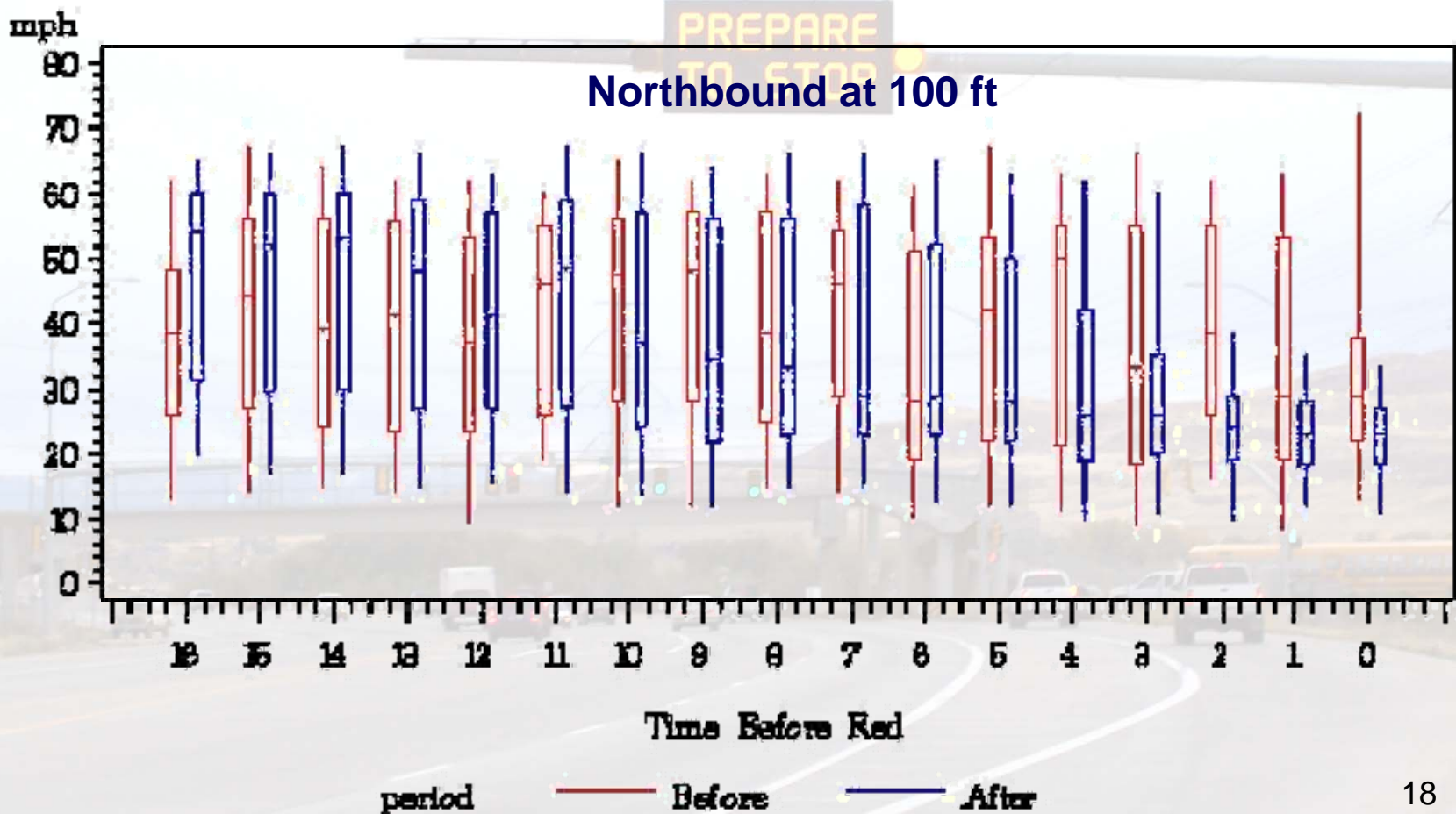
**Immediately After, Northbound, 100 ft**



# EFFECTIVENESS

*Preliminary Results at 13400 South*

- Speed data box plots:



# EFFECTIVENESS

*Preliminary Results at 13400 South*

- Speed data statistical significance grids:

	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	NB	Evening
300																			
200																			
100																			
50																			

	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	NB	Afternoon
300																			
200																			
100																			
50																			

	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	NB	Morning
300																			
200																			
100																			
50																			

# EFFECTIVENESS

*Preliminary Results at 13400 South*

- Red-light running data results:

	Before	% of Total	After	% of Total	% Change	Probability
NB	5.626	0.56	1.233	0.12	-78%	< .0001
SB	1.806	0.18	0.497	0.049	-72%	< .0001

\*Red-light running events per 1,000 entering vehicles (single approach stop bar counts only)

- RLR data was filtered with 4-second after red and 20 mph speed thresholds
- UDOT manual counts used to verify sensor data



# EFFECTIVENESS

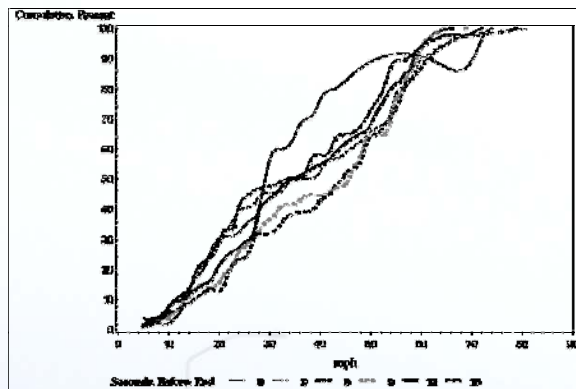
## *Preliminary Conclusions*

- AWS signs appear to affect driver behavior even when they are not flashing
- Motorists were traveling at higher and more constant speeds before the signs came on
- Motorists were slowing down and more motorists were stopping after the light turned yellow
- The total number of red-light runners at the intersections was reduced immediately after system activation

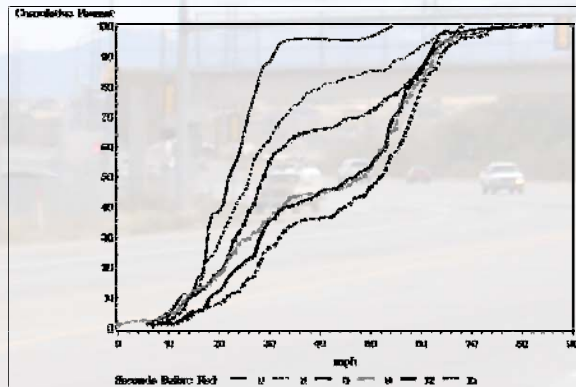
# EFFECTIVENESS

*Eight-month After Results*

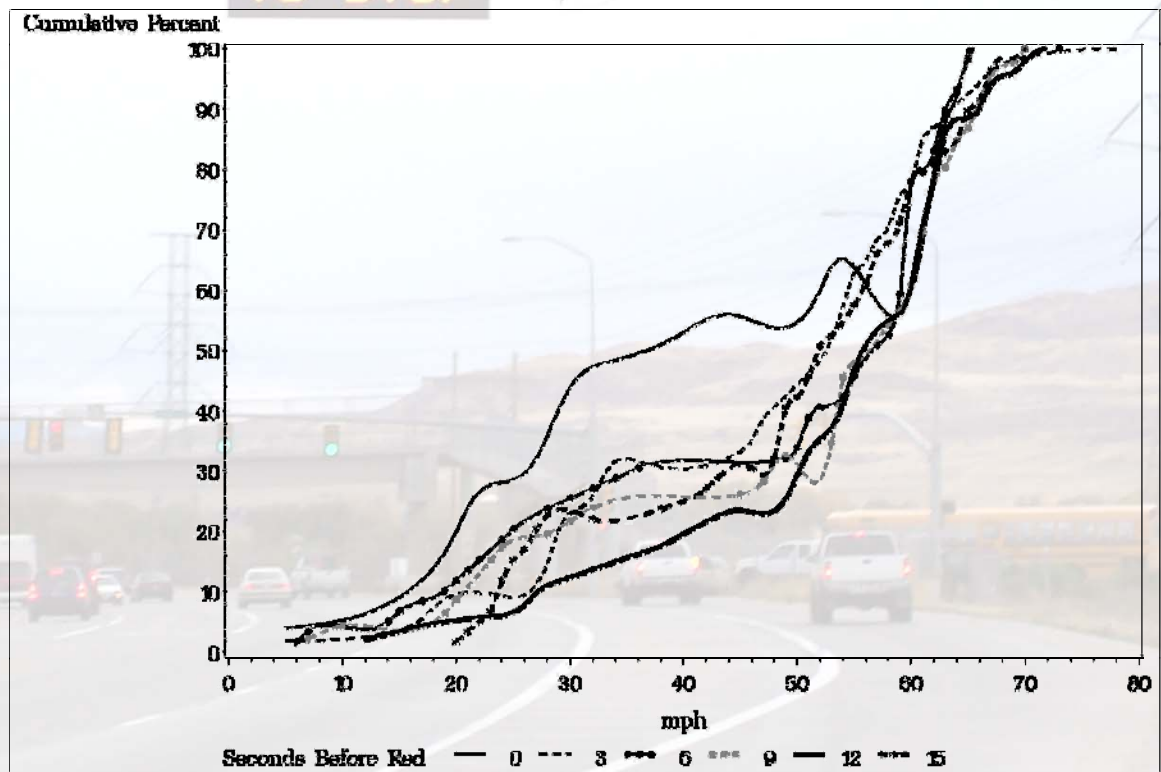
**Before**



**Immediately After**

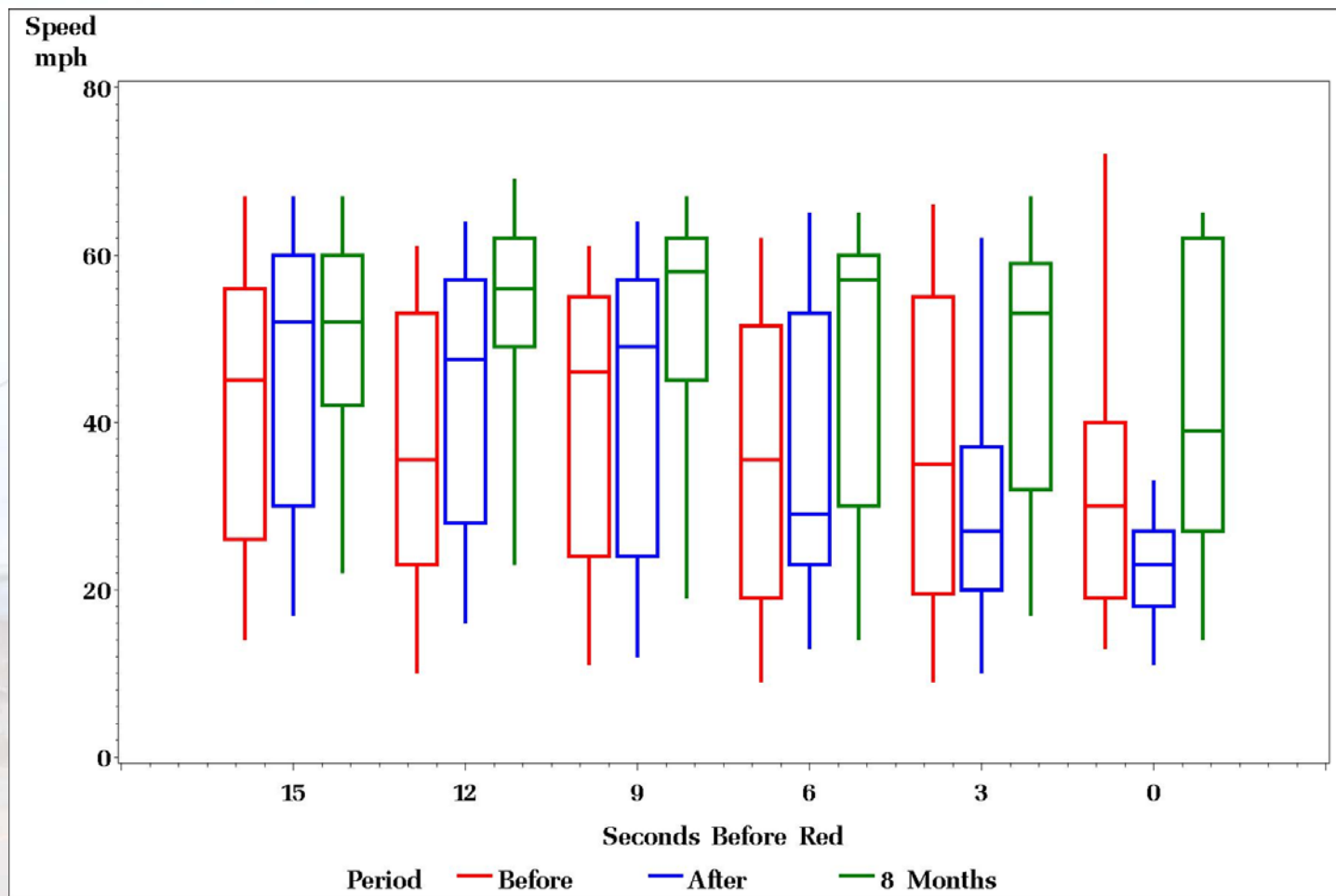


**8-Months After**



# EFFECTIVENESS

*Eight-month After Results*



# EFFECTIVENESS

*Eight-month After Results*

- Eight months after the system was installed:
  - Speed distributions returned to similar trends as before installation
  - Red light running increased to levels slightly higher than before installation in some instances
  - Crash rates decreased
  - Decision zone remained relatively constant
- Lead flash time theorized to be too conservative



# FUTURE RESEARCH

- Modify lead-flash timing and evaluate effectiveness:
  - Monthly evaluation
  - Monitor six to eight months after final changes made
- Follow-up research project:
  - Establish guidelines for future installations
  - Identify locations that fall within guidelines
  - Prioritize locations for future installations

$$t_{F(DCZ)} = \frac{D_M + D_P}{v_0} - DCZ_n$$

# QUESTIONS?

- For more information, contact:

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